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1.2. Linear Programming: A Graphical Perspective in R² 13 The feasible region is shown in Figure 1.4. The LP has alternative optimal solutions that fall on the segment connecting $x = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ to $x = \begin{pmatrix} 6 \\ 0 \end{pmatrix}$. Each such solution has an objective value of $z = 12$, and the parametric representation of the segment is given by $x = \begin{pmatrix} 3t+6(1-t) \\ 1-t \end{pmatrix}$

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piecewise linear is represented by the following equation and the x-y axis graph of the piecewise linear is also shown below.

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